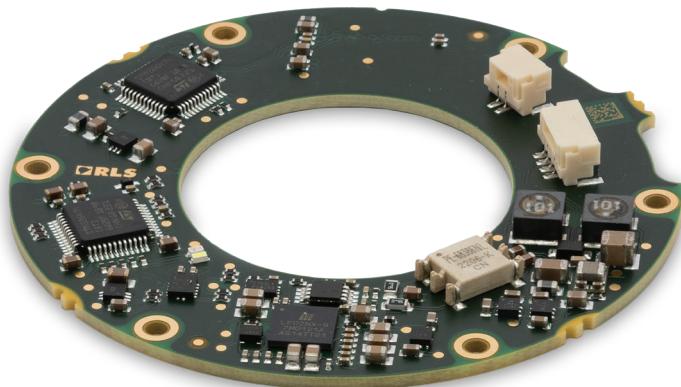


## AksIM-4™



## with Hiperface DSL Protocol

The AksIM-4 is a non-contact, high performance off-axis absolute rotary encoder. It is designed for integration into applications with limited space. A hollow ring, true absolute functionality and Hiperface DSL protocol make this encoder suitable for compact servo motor applications. The AksIM-4 encoder system consists of an axially magnetised ring and a readhead.



**Samples available**

### Why choose AksIM-4™ with Hiperface DSL Protocol?

#### FEATURES:

- ✓ True absolute
- ✓ Custom magnetic sensor ASIC
- ✓ Self-calibration option
- ✓ Low profile
- ✓ Non-contact

#### BENEFITS:

- ✓ Reduced wiring complexity
- ✓ High speed data transmission
- ✓ Cost efficient
- ✓ Possibility for more compact motor design
- ✓ One cable technology protocol



ASSEMBLY LINES



MOTOR  
FEEDBACK



INDUSTRIAL  
AUTOMATION



SPINDLES



INDUSTRY 4.0

# AksIM-4™ Hiperface DSL technical specifications

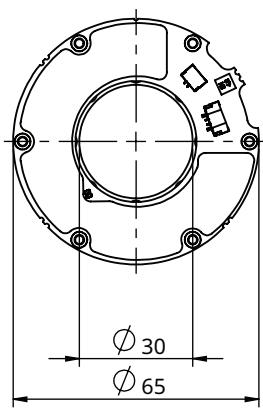
SYSTEM DATA		
Reading type	Axial reading	
Resolution	20 bit	
Maximum speed	MRA053: 7,500 rpm MRA080: 4,700 rpm	
System accuracy	Up to $\pm 0.005^\circ$ / $\pm 18$ arcsec	
ELECTRICAL DATA		
Supply voltage	7 V to 12 V at the connector	
Current consumption	Typ. 85 mA at 12 V - at the connector, max 1.4 W	
MECHANICAL DATA		
Available ring sizes (ID)	30 mm, 55 mm, 64 mm	
Material type	EN 1.4016 / AISI430 with glued CPE rubber filled with ferrite particles	
ENVIRONMENTAL DATA		
Operating and storage temperature	Readhead Ring	-40 °C to +115 °C -40 °C to +105 °C

## AksIM-4™ Hiperface DSL dimensions

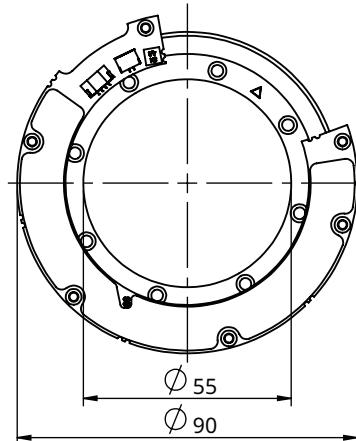
Dimensions and tolerances are in mm. Dimensions without tolerance values are in accordance with ISO 2768-m. System thickness is 9.05 mm for both sizes.



MC053 readhead with MRA053 ring



MC080 readhead with MRA080 ring



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