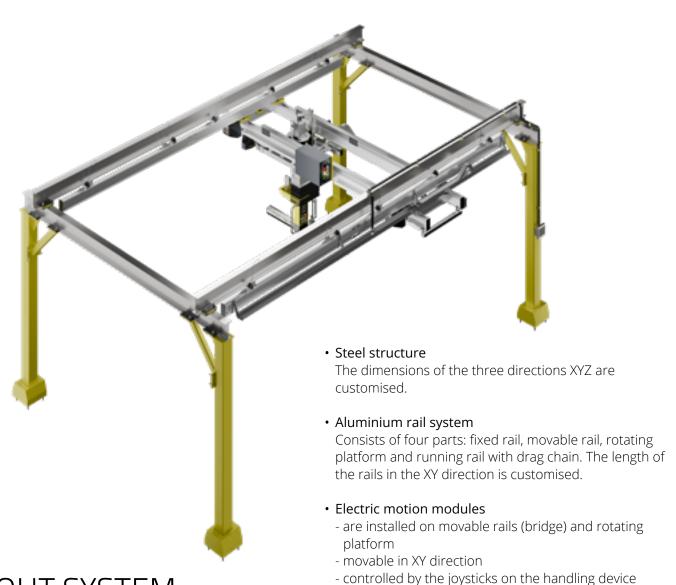
#### **OHT SYSTEM**



The OverHead Transport system is a system for loading and unloading electrode rolls, but other applications are also possible. It is easy and ergonomic to operate and is precise and fast. The dimensions of the workspace can be customised. The system can be integrated into a production line.



### **OHT SYSTEM**

Consists of five main components: Steel structure, aluminium rail system, lifting system, tooling, electric drive modules.

# Lifting system

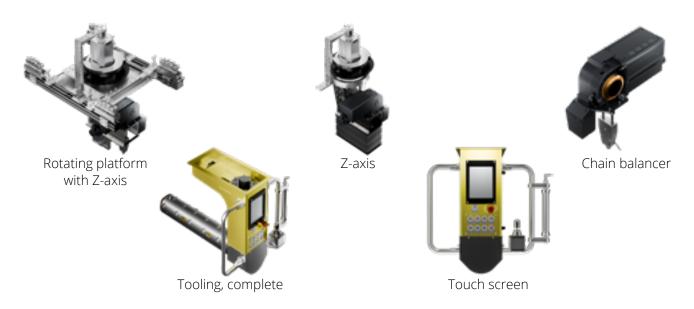
Consists of the following parts: endlessly rotating Z-axis, rotating platform with rotary joint, electronic chain balancer, bellows, brakes, drag chain.

#### Tooling

Consists of the following parts: Basic fixture, touch screen, button group, operating handle, joystick, pressure and clamping mechanism, position detection, camera for positioning, locking mechanism.

## **OHT SYSTEM**





| Techncal Data                    |  |
|----------------------------------|--|
| Load capacity                    | max. 900 kg (other weights on request)                       |
| Power supply                     | 230 V / 3.800 VA   |
| Lifting motor                    | Chain balancer with AC motor (AC)                            |
| Standard stroke                  | 2.000 mm   |
| Lifting speed                    | max. 150 mm/s  |
| 3 Drives XY direction            | AC motors (AC)   |
| Power supply per drive           | 230 V / 440 VA   |
| Motion in XY direction:          | Electronic control of the direction of travel with direction |
|                                  | detection  |
| Travelling speed in XY direction | max. 163,3 mm/s  |
| Z-axis                           | endlessly rotatable  |
| Installation                     | Mounting on steel construction, floor or ceiling mounting    |
| Dimensions of the workspace      | Length mx. 35 m / width max. 11 m                            |
|                                  | (dimensions will be customised)                              |
| Options                          | - Positioning options via camera / sensors                   |
|                                  | - Rotation angle limitation of the Z-axis (4x 90°)           |
|                                  | - Manual bridge movement                                     |

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