

# **Compact LiDAR LSC Series**

The perfect Solution for Presence Detection







# LSC Series

LiDAR sensors utilize time-of-flight (ToF) method to measure the round trip time of the infrared laser beam, to accurately detect presence of objects within a wide range area.

As the logistics robots and service market has grown, interest in LiDAR sensors is increasing. This technology can be applied in various industries such as AGV, OHT, drone, automobile, aircraft, and satellite to detect the surrounding environment, autonomous driving, collision prevention, and entrances. In addition, LiDAR sensors are highly utilized to detect objects within a wide range flexibly and accurately.

The new LSC series LiDAR sensors from Autonics is available in 3 detection distance models (5 m / 10 m / 25 m). The compact size makes it optimal for use in small and medium-sized equipment. The laser scanners feature horizontal 270° detection area, angular resolution of 0.33°, and uses a 905 nm laser to meet Laser Class 1 for precise detection and measurement.

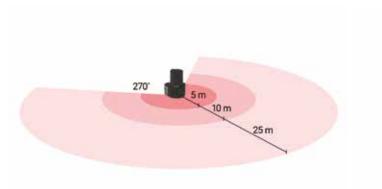
The scanners offer 16 field sets and teaching function for flexible installation and Ethernet / Bluetooth communication allows easy configuration with PC and mobile application. The ROS (Robot Operation System) driver is also supported for SLAM (Simultaneous Localization and Mapping) function of AGV/AMR.

# Main Features

 Wide range detection area : 270° detection angle, 25 m detection distance Number of field sets : 16 (1 set : consists of 3 subfields) Various filter function for accurate detection Compact size for flexible installation (L60 x W60 x H86mm) Ethernet and Bluetooth communication • atLiDAR software provided for PC and Android devices • ROS, API supported

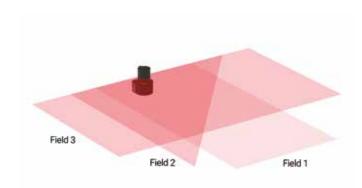
\* Bluetooth model availability may differ by country

# **Detailed Features**



## 270° Detection Angle, 25 m Detection Distance

The LSC series laser scanners offer wide range detection area with horizontal 270° detection angle and up to 25 m detection distance.



## Flexible Field Configuration

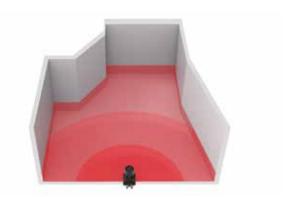
The laser scanners can set 16 types of field sets with 4 input types. Each field set consists of 3 sub-fields and each sub-field are individually connected to outputs.



## Easy Parameter Setting with Mobile Application

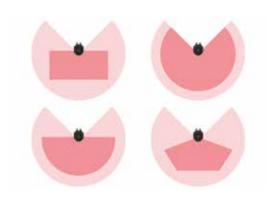
The LSC series offer Bluetooth communication for parameter setting with mobile (Android) devices.

\* Bluetooth model availability may differ by country



### Auto Set Detection Area with Teaching Function

Users can use the teaching function to automatically set optimal detection area. This function can be operated also with dedicated software and other input signals.



## Intuitive Detection Format Setting

Each sub-field can be configured in the form of rectangles, circles and polygons for easy and flexible application.



# Dedicated Software atLiDAR Provided

Users can easily set parameters and monitor status with dedicated software atLiDAR. The intuitive and user-friendly interface allows users to easily operate laser scanners.

# Application



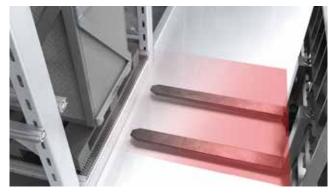
### Autonomous Mobile Robot

Laser scanners are used in Automated Guided Vehicle and Autonomous Mobile Robot to prevent collisions with personnel and objects. (Overhead Hoist Transport) equipment operation.



### Interactive Media

Laser scanners can be used in various interactive contents for education, promotion, arts and more.



# **Environment Detection**

Laser scanner can be used to detect occupancy status of tray and to

Laser scanners are used to identify the inner condition of tote boxes detect size of pallet for pick-up.



# Collision Prevention

Laser scanners used to prevent collisions between objects in OHT



## Security

Laser scanners used for security purposes at retail stores.



# Abnormality Detection

on shipping conveyor belts.

# Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

LSC -0 0 **8 4** Scan angle Control output 2 Detection distance **⑤** Ethernet TCP/IP Number: Detection distance (unit: m)

LSC-C5CT3-ET LSC-C10CT3-ET LSC-C25CT3-ET

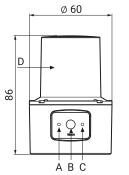
# **Specifications**

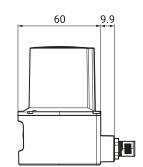
Connection

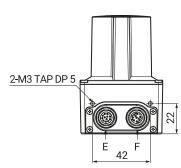
| Emitting property   | Infrared laser  |   |   |  |  |  |
|---|---|---|---|--|--|--|
| Laser class   | CLASS 1   |   |   |  |  |  |
| Wave length band  | 905 nm  |   |   |  |  |  |
| Max. pulse output power   | 6 W   |   |   |  |  |  |
| Light beam emitting angle   | 14.5 mrad   |   |   |  |  |  |
| Scanning frequency  | 15 Hz   |   |   |  |  |  |
| Response time   | Typ. 67 ms  | Typ. 67 ms  |   |  |  |  |
| Detection distance range  | 0.05 to 5 m   | 0.05 to 10 m  | 0.05 to 25 m  |  |  |  |
| Detection distance of 10 % Reflector  | 5 m   | 8 m   |   |  |  |  |
| Detection distance error  | System error: Typ. ± 6  | System error: Typ. ± 60 mm, statistical error: Typ. 20 mm (1 σ)   |   |  |  |  |
| Min. object size 01)  | At detection distance of 8 m: ≈ 121 mm  |   |   |  |  |  |
| Angular resolution  | 0.33°   |   |   |  |  |  |
| Aperture angle  | 270°  | 270°  |   |  |  |  |
| Object reflectivity   | > 4 %   |   |   |  |  |  |
| Number of field sets  | 16 (1 set: Consists of subfields 1,2,3)   |   |   |  |  |  |
| Number of field sets that can be used concurrently  | 1   |   |   |  |  |  |
| Unit weight (package)   | ≈ 228 g (314 g)   |   |   |  |  |  |
| Certification   | CE EK IS  |   |   |  |  |  |
| Even objects smaller than the se  | et min. object size can be dete   | cted depending on the environmer  | nt.   |  |  |  |
|   | 9 - 28 VDC  |   |   |  |  |  |
| Power supply  | 9 - 28 VDC==  |   |   |  |  |  |
| Power supply  Power consumption 01)   | 9 - 28 VDC===<br>< 4 W  |   |   |  |  |  |
| ,   | < 4 W   | - H: ≥ 9 - 28 VDC, L: ≤ 3 VE  | DC  |  |  |  |
| Power consumption 01) Input Output signal   | < 4 W<br>4 Photocoupler inputs<br>4: 3-output + 1-Ready   |   | DC=   |  |  |  |
| Power consumption <sup>01)</sup> Input  | < 4 W<br>4 Photocoupler inputs<br>4: 3-output + 1-Ready   | Error, Sync output  | )C==  |  |  |  |
| Power consumption 01) Input Output signal   | < 4 W 4 Photocoupler inputs 4: 3-output + 1-Ready, NPN-PNP open collect   | Error, Sync output  | DC==  |  |  |  |
| Power consumption (01) Input Output signal Load voltage   | < 4 W 4 Photocoupler inputs 4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC==  | Error, Sync output  | )C=-  |  |  |  |
| Power consumption <sup>01)</sup> Input Output signal Load voltage Load current  | < 4 W  4 Photocoupler inputs  4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC ≤ 100 mA   | Firror, Sync output<br>or output setting (software)   | )C=-  |  |  |  |
| Power consumption on Input Output signal Load voltage Load current Residual voltage   | < 4 W  4 Photocoupler inputs  4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC: ≤ 100 mA ≤ 3.0 VDC: ≥ 5 MΩ (500 VDC:= m   | Firror, Sync output<br>or output setting (software)   |   |  |  |  |
| Power consumption oil Input Output signal Load voltage Load current Residual voltage Insulation resistance  | < 4 W  4 Photocoupler inputs 4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC: ≤ 100 mA ≤ 3.0 VDC: ≥ 5 MΩ (500 VDC: m  Between the charging   | 'Error, Sync output<br>or output setting (software)<br>egger)   | ∼ 50 / 60 Hz for 1 minute   |  |  |  |
| Power consumption on Input Output signal Load voltage Load current Residual voltage Insulation resistance Dielectric strength   | < 4 W  4 Photocoupler inputs 4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC == ≤ 100 mA ≤ 3.0 VDC == ≥ 5 MΩ (500 VDC == m) Between the charging 10 sweep cycles in each   | Fror, Sync output or output setting (software) egger) part and the case: 500 VAC-   | ∼ 50 / 60 Hz for 1 minute 0 to 500 Hz, acceleration 5 G   |  |  |  |
| Power consumption on Input Output signal Load voltage Load current Residual voltage Insulation resistance Dielectric strength Vibration Vibration (malfunction) Vibration (irregular)   | < 4 W  4 Photocoupler inputs 4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC == ≤ 100 mA ≤ 3.0 VDC == ≥ 5 MΩ (500 VDC == m) Between the charging 10 sweep cycles in eac 10 minutes in each X,  | YError, Sync output<br>or output setting (software)<br>egger)<br>part and the case: 500 VAC:<br>h X, Y, Z axes at sine wave, 10   | ∼ 50 / 60 Hz for 1 minute 0 to 500 Hz, acceleration 5 G 500 Hz, acceleration 5 G  |  |  |  |
| Power consumption oil Input Output signal Load voltage Load current Residual voltage Insulation resistance Dielectric strength Vibration Vibration (malfunction) Vibration (irregular)  | < 4 W  4 Photocoupler inputs 4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC== ≤ 100 mA ≤ 3.0 VDC== ≥ 5 MΩ (500 VDC== m  Between the charging 10 sweep cycles in each X, Y, Z 3 times in each X, Y, Z 1000 times in each X, Y, S 5000 times in each X, Y, S  | regger) part and the case: 500 VAC- h X, Y, Z axes at sine wave, 10 to axes at 5 to 250 Hz, 42.4 m, axes at 5 sine half wave, acceler y, Z axes at sine half wave, acc, z axes at sine half wave, acc | ~ 50 / 60 Hz for 1 minute 0 to 500 Hz, acceleration 5 G 1500 Hz, acceleration 5 G /s RMS ration 50 G, duration 11 ms celeration 25 G, duration 6 ms celeration 50 G, duration 3 ms  |  |  |  |
| Power consumption on Input Output signal Load voltage Load current Residual voltage Insulation resistance Dielectric strength Vibration Vibration (malfunction) Vibration (irregular)   | < 4 W  4 Photocoupler inputs 4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC== ≤ 100 mA ≤ 3.0 VDC== ≥ 5 MΩ (500 VDC== m  Between the charging 10 sweep cycles in each X, Y, Z 3 times in each X, Y, Z 1000 times in each X, Y, S 5000 times in each X, Y, S  | regger) part and the case: 500 VAC- h X, Y, Z axes at sine wave, 10 to axes at 5 to 250 Hz, 42.4 m, uxes at sine half wave, acceler, Z axes at sine half wave, acceler, Z axes at sine half wave, acceler, Z axes at sine half wave, acceler,   | ~ 50 / 60 Hz for 1 minute 0 to 500 Hz, acceleration 5 G 1500 Hz, acceleration 5 G /s RMS ration 50 G, duration 11 ms celeration 25 G, duration 6 ms celeration 50 G, duration 3 ms  |  |  |  |
| Power consumption oil Input Output signal Load voltage Load current Residual voltage Insulation resistance Dielectric strength Vibration Vibration (malfunction) Vibration (irregular)  | < 4 W  4 Photocoupler inputs 4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC== ≤ 100 mA ≤ 3.0 VDC== ≥ 5 MΩ (500 VDC== m  Between the charging 10 sweep cycles in each X, Y, Z 3 times in each X, Y, Z 1000 times in each X, Y, S 5000 times in each X, Y, S  | regger) part and the case: 500 VAC- h X, Y, Z axes at sine wave, 10 to axes at 5 to 250 Hz, 42.4 m, axes at 5 sine half wave, acceler y, Z axes at sine half wave, acc, z axes at sine half wave, acc | ~ 50 / 60 Hz for 1 minute 0 to 500 Hz, acceleration 5 G 1500 Hz, acceleration 5 G /s RMS ration 50 G, duration 11 ms celeration 25 G, duration 6 ms celeration 50 G, duration 3 ms  |  |  |  |
| Power consumption oil Input Output signal Load voltage Load current Residual voltage Insulation resistance Dielectric strength Vibration Vibration (malfunction) Vibration (irregular) Shock Shock (malfunction)  | < 4 W  4 Photocoupler inputs 4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC== ≤ 100 mA ≤ 3.0 VDC== ≥ 5 MΩ (500 VDC== m Between the charging 10 sweep cycles in each X, Y, Z & 3 times in each X, Y, Z & 1000 times in each X, Y, Z & ≤ 80,000 lx  | regger) part and the case: 500 VAC- h X, Y, Z axes at sine wave, 10 to axes at 5 to 250 Hz, 42.4 m, axes at 5 sine half wave, acceler y, Z axes at sine half wave, acc, z axes at sine half wave, acc | ~ 50 / 60 Hz for 1 minute 0 to 500 Hz, acceleration 5 G 1500 Hz, acceleration 5 G /s RMS ration 50 G, duration 11 ms celeration 25 G, duration 6 ms celeration 50 G, duration 11 ms   |  |  |  |
| Power consumption on Input Output signal Load voltage Load current Residual voltage Insulation resistance Dielectric strength Vibration Vibration (malfunction) Vibration (irregular) Shock Shock (malfunction) Ambient illuminance                                       | < 4 W  4 Photocoupler inputs 4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC== ≤ 100 mA ≤ 3.0 VDC== ≥ 5 MΩ (500 VDC== m Between the charging 10 sweep cycles in each X, Y, Z 3 times in each X, Y, Z 1000 times in each X, Y, Z ≤ 80,000 lx -10 to 50 °C, storage: -   | egger) part and the case: 500 VAC- h X, Y, Z axes at sine wave, 10 t axes at 5 to 250 Hz, 42.4 m, xxes at sine half wave, acceler Z axes at sine half wave, acceler Z axes at sine half wave, acceler Z axes at sine half wave, acceler   | ~ 50 / 60 Hz for 1 minute 0 to 500 Hz, acceleration 5 G 1500 Hz, acceleration 5 G /s RMS ration 50 G, duration 11 ms releration 25 G, duration 6 ms reteration 50 G, duration 11 ms ration 50 G, duration 11 ms ondensation)                |  |  |  |
| Power consumption o1) Input Output signal Load voltage Load current Residual voltage Insulation resistance Dielectric strength Vibration Vibration (malfunction) Vibration (irregular) Shock Shock (malfunction) Ambient illuminance Ambient temperature                  | < 4 W  4 Photocoupler inputs 4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC== ≤ 100 mA ≤ 3.0 VDC== ≥ 5 MΩ (500 VDC== m Between the charging 10 sweep cycles in each X, Y, Z 3 times in each X, Y, Z 1000 times in each X, Y, Z ≤ 80,000 lx -10 to 50 °C, storage: -   | egger) part and the case: 500 VAC- h X, Y, Z axes at sine wave, 10 to axes at 5 to 250 Hz, 42.4 m, xes at sine half wave, acceler Z axes at sine half wave, acceler axes at sine half wave, acceler X axes at sine half wave, acceler   | ~ 50 / 60 Hz for 1 minute 0 to 500 Hz, acceleration 5 G 1500 Hz, acceleration 5 G /s RMS ration 50 G, duration 11 ms releration 25 G, duration 6 ms reteration 50 G, duration 11 ms ration 50 G, duration 11 ms ondensation)                |  |  |  |
| Power consumption oil Input Output signal Load voltage Load current Residual voltage Insulation resistance Dielectric strength Vibration Vibration (malfunction) Vibration (irregular) Shock Shock (malfunction) Ambient illuminance Ambient temperature Ambient humidity | < 4 W  4 Photocoupler inputs 4: 3-output + 1-Ready, NPN-PNP open collect 9 - 28 VDC== ≤ 100 mA ≤ 3.0 VDC== ≥ 5 MΩ (500 VDC== m Between the charging 10 sweep cycles in each X, Y, Z 3 times in each X, Y, Z 3 times in each X, Y, Z 4 times in each X, Y, Z 5 knours in each X, Y, Z 6 times in each X, Y, Z ≤ 80,000 lx -10 to 50 °C, storage: 0 to 95 %RH, storage: | regger) part and the case: 500 VAC- h X, Y, Z axes at sine wave, 10 to axes at 5 to 250 Hz, 42.4 m, xes at sine half wave, acceler Z axes at sine half wave, acceler axes at sine half wave, acceler C to 50 % RH (no freezing or c                     | ~ 50 / 60 Hz for 1 minute 0 to 500 Hz, acceleration 5 G 1500 Hz, acceleration 5 G /s RMS ration 50 G, duration 11 ms releration 25 G, duration 6 ms releration 50 G, duration 11 ms ration 50 G, duration 11 ms ration 50 G, duration 11 ms |  |  |  |

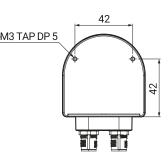
# Dimensions

\*Unit: mm, For the detailed drawings, follow the Autonics website.









| Α | Power indicator     | D | Window                |  |
|---|---------------------|---|-----------------------|--|
| В | Teaching button     | Е | Power I / O connector |  |
| С | Detection indicator | F | Ethernet connector    |  |

# **Autonics**

# Global Network

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# **Products**

### Sensors, Controllers, Motion Devices, Safety, Measuring Equipment, Connection Equipment and more

- Photoelectric Sensors Photomicro Sensors Fiber Optic Sensors Door Sensors Area Sensors Proximity Sensors LiDAR
- $\cdot \ Displacement \ Sensors \cdot \ Ultrasonic \ Sensors \cdot \ Rotary \ Encoders \cdot \ Temperature \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Sensors \cdot \ Temperature \ Transmitters \cdot \ Pressure \ Temperature \ Temperature$
- $\cdot \text{Pressure Transmitters} \cdot \text{Smart Camera} \cdot \text{Vision Sensors} \cdot \text{Safety Light Curtains} \cdot \text{Safety Door Switches} \cdot \text{Safety Switches} \cdot \text{Safety Controllers} \cdot \text{Temperature Controllers} \cdot \text{Solid State Relays} \cdot \text{Power Controllers} \cdot \text{Counters} \cdot \text{Digital Panel Meters}$
- $\cdot \text{Digital Display Units} \cdot \text{Sensor Controllers} \cdot \text{SMPS} \cdot \text{Industrial PC} \cdot \text{HMIs} \cdot \text{Recorders} \cdot \text{Indicators} \cdot \text{Network Converters}$
- Closed Loop Stepper Motor System 5-Phase Stepper Motor & Drivers 2-Phase Stepper Motor Drivers Motion Controllers
- $\cdot \ \, \text{Industrial Networking} \cdot \text{I/O Terminal Blocks} \cdot \text{Distribution Boxes} \cdot \text{Cables} \cdot \text{Control Switches} \, / \, \text{Pilot Lights} \, / \, \text{Buzzers} \cdot \text{Software Boxes} \cdot \text{Cables} \cdot \text{Control Switches} \, / \, \text{Pilot Lights} \, / \, \text{Buzzers} \cdot \text{Software Boxes} \cdot \text{Cables} \cdot \text{Control Switches} \, / \, \text{Pilot Lights} \, / \, \text{Buzzers} \cdot \text{Software Boxes} \cdot \text{Cables} \cdot \text{Control Switches} \, / \, \text{Pilot Lights} \, / \, \text{Buzzers} \cdot \text{Software Boxes} \cdot \text{Cables} \cdot \text{Control Switches} \, / \, \text{Pilot Lights} \, / \, \text{Buzzers} \cdot \text{Software Boxes} \cdot \text{Cables} \cdot \text{Control Switches} \, / \, \text{Pilot Lights} \, / \, \text{Buzzers} \cdot \text{Software Boxes} \, / \, \text{Cables} \cdot \text{Control Switches} \, / \, \text{Pilot Lights} \, / \, \text{Buzzers} \cdot \text{Software Boxes} \, / \, \text{Cables} \cdot \text{Control Switches} \, / \, \text{Pilot Lights} \, / \, \text{Control Switches} \, / \, \text{Pilot Lights} \, / \, \text{Control Switches} \, / \, \text{Control Switches} \, / \, \text{Pilot Lights} \, / \, \text{Control Switches} \, / \, \text{Control Switches} \, / \, \text{Pilot Lights} \, / \, \text{Control Switches} \, / \, \text{Cont$
- \* The dimensions or specifications on this product guide may change and some models may be discontinued without notice. 202310-LSC Product Flyer-EN-01