

SMART GRIPPER



Sees

Detection of workpiece to be gripped Detection of approaching objects



Analyses

Force control
Position control
Speed control
Predictive maintenance
Programmable gestures

Communicates

Fieldbus communication
Wireless and
NFC communication
Visual communication (LED)



Perceives

Measurement of the workpiece weight Measurement of the workpiece size Anti-slip grip function

Connects

Mechanical and electric connection for cobot and industrial plug & play robots JOINT LAB WITH



Camozzi's Smart Gripper integrates an innovative technological concept with the functions of a hand, combining flexibility, efficiency, ergonomics and intelligence all in one device.

It is able to perceive objects, to analyse and estimate their weight, size and distance.

The gripper was developed at the joint Camozzi and IIT Istituto Italiano di Tecnologia of Genoa laboratory.

Contacts

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